

10W Anti-crackling mono Audio amplifier

9W Mono AB Audio amplifier

-Features

- Anti-clipping function (Anti-Clipping Function, ACF) • Filter-free digital modulation, direct speaker drive
- Output Power
10W (Class D, $V_{DD}=8.5V$, $R_L=4\Omega$, $THD+N=10\%$) 9W (Class AB, $V_{DD}=8.5V$, $R_L=4\Omega$, $THD+N=10\%$) • have D Class and AB Two working modes
- Overcurrent protection function
- Overheat protection function
- Undervoltage abnormal protection function
- Lead-free and halogen-free packaging, SOP8L-PP

-application

- Bluetooth Speaker
- 2.1 Channel small speaker
- iPhone/iPod/iPod docking
- Tablet, Laptop
- Small size LCD TV/Monitor
- Portable Speakers
- Loudspeaker
- Trolley Speaker
- Portable game console
- MP4, GPS

-Overview

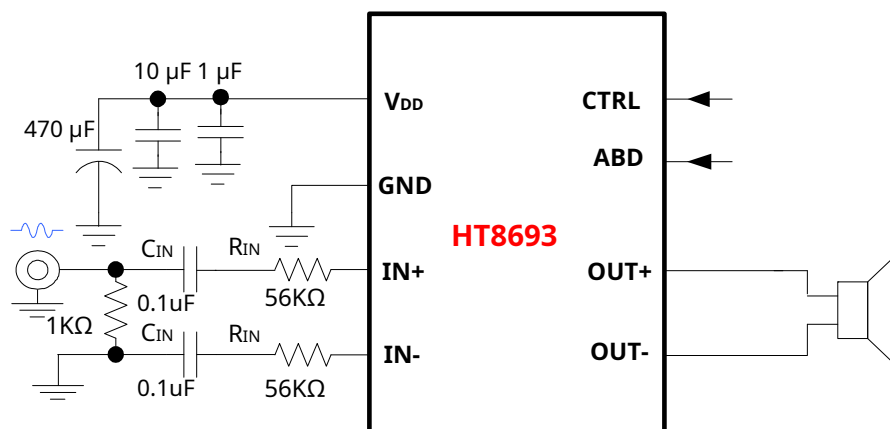
HT8693 is a D Class and AB Class audio power amplifier with two working modes. In class mode, $V_{DD}=8.5V$, $THD+N=10\%$, 4Ω Under load, it can continuously output 10W power; In class mode, $V_{DD}=8.5V$, $THD+N=10\%$, 4Ω Under load, it can continuously output 9W power.

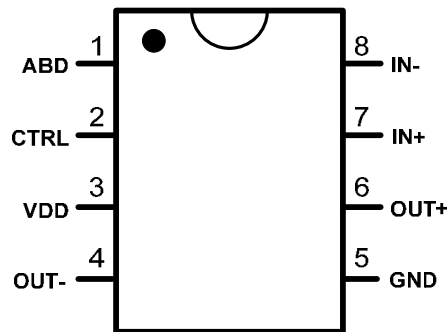
HT8693 exists D Anti-clipping distortion in similar working mode (ACF) output control function, which can detect and suppress the output signal clipping distortion (breaking) caused by excessive amplitude of input music and voice signals. (Sound), significantly improve the sound quality, create a comfortable listening experience, and protect the speaker from overload damage. At the same time, the chip also has ACF-Off Mode is configurable.

HT8693 can achieve AB Class and D The free switching function of the class is affected by D Class Amplifier EMI. When you are bothered by interference, you can switch to AB Audio amplifier mode.

also, HT8693 The built-in shutdown function minimizes the standby current, and also integrates functions such as output overcurrent protection, on-chip overtemperature protection and power supply undervoltage abnormal protection.

-Typical application diagram



-Pin Information


顶视图

-Pin Definition*1

SOP8L-PP Pin Number	Pinout name	I/O	Function
1	ABD	I	ABClass Mode andDCClass Mode Controller
2	CTRL	I	ACFMode and shutdown mode control terminal
3	VDD	Power	power supply
4	OUT-	O	Inverting output terminal (BTL-)
5	GND	Ground	land
6	OUT+	O	Non-inverting output terminal (BTL+)
7	IN+	A	Non-inverting input terminal (differential +)
8	IN-	A	Inverting input terminal (differential -)

Note1 I:Input O:Output A:Analog terminal

When greater thanVDDThe voltage applied toPNProtected port (ESDPProtection circuit byPMOSandNMOSWhenPMOSA leakage current will flow through the circuit.

-Ordering Information

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Package

Product number	Package	Top surface mark	range of working temperature	Packaging and delivery form
HT8693SP	SOP8L-PP	HT8693SP UVWXYZ*2	- 40°C~85°C (Extended Industrial Grade)	Tube 100Sheet/Tube

Note2:WXYZ/UVWXYZRandomly coded for internal production tracking.

Note3: Unless otherwise specified, the data content on the following pages is forSOP8L-PPPPackageHT8693Model product.

Electrical characteristics
Extreme working conditions*1

parameter	symbol	Minimum	Maximum	unit
Supply voltage range	V _{DD}	- 0.3	9.3	V
Input signal voltage range (IN+, IN-)	V _{IN}	V _{SS} -0.6	V _{DD} +0.6	V
Input signal voltage range (except IN+, IN-outside)	V _{IN}	V _{SS} -0.3	V _{DD} +0.3	V
Operating temperature range	T _A	- 40	85	°C
Operating junction temperature range	T _J	- 40	150	°C
Storage temperature	T _{STG}	- 50	150	°C

Note1: To ensure device reliability and life, the above absolute maximum ratings must not be exceeded. Otherwise, the chip may be immediately permanently damaged or its reliability may be greatly deteriorated.

In possibly more than V_{DD}/GND for applications where the voltage is too high, it is recommended to use an external diode to ensure that the voltage does not exceed the absolute maximum rating.

Recommended operating conditions

parameter	symbol	condition	Minimum	Typical Value	Maximum	unit
voltage*2	V _{DD}		3		9.0	V
Working temperature	T _a		- 40	25	85	°C
Speaker impedance	R _L			4		Ω

Note2: V_{DD} The rise time should exceed 1μs.

Electrical characteristics*

V_{SS}=0V, T_a=25°C, C_{IN}=0.1μF, R_{IN}= 56k, Unless otherwise specified

parameter	symbol	condition	Minimum	Typical Value	Maximum	unit
V _{DD} Power supply start threshold	V _{UVL}			2.3		V
V _{DD} Power supply shutdown threshold	V _{UVLL}			2.2		V
Power-on start-up time (or from off Wake-up time)	t _{STUP}			280		ms
Carrier modulation frequency	f _{PWM}			430		kHz
DClass overcurrent protection value	I _{max}				5	A
Digital Input/Output						
ABDInput high level	V _{IH}		1.5			V
ABDInput low level	V _{IL}				0.4	V
CTRLInternal pull-down resistor	R _{CTRL}	Class D		125		KΩ
		Class AB		+ ∞		
ABDInternal pull-up resistor	R _{ABD}			250		KΩ
ACF Function						
Class D ACFAttenuation Gain	A _a		- 16		0	dB
ACF-OffMode Setting Threshold	V _{MOD1}		0.75V _{DD}		V _{DD}	V
ACF-1Mode Setting Threshold*4	V _{MOD2}		0.45 V _{DD}		0.70 V _{DD}	V
ACF-2Mode Setting Threshold*4	V _{MOD3}		0.10 V _{DD}		0.40 V _{DD}	V
SDShutdown Mode Setting Threshold	V _{MOD4}		V _{SS}		0.06 V _{DD}	V
SDShutdown recovery voltage*5	V _{CTRL_ON}		0.8			V

Note3: The electrical characteristics in this section vary depending on the components and PCB layout.

Note4: ACF-1 and ACF-2 Mode only for DClass mode is effective in AB. In the class mode, the corresponding level mode is still ACF-Off. Note5: SD The shutdown recovery voltage refers to the voltage when the chip goes from shutdown to startup. CTRL The voltage value of the terminal.

V_{DD} = 8.5V

parameter	symbol	condition	Minimum	Typical Value	Maximum	unit
Class D Channel V _{SS} =0V, Av=26dB, Ta=25°C, C _{IN} =0.1uF, ACF-OffMode, unless otherwise specified						
Output Power	P _O	R _L =4Ω	f=1kHz, THD+N=10%		10.0	W
		R _L =8Ω			5.3	
		R _L =4Ω,	f=1kHz, THD+N=1%		8.0	
		R _L =8Ω			4.3	
Total Harmonic Distortion plus Noise	THD+N	P _O =0.1W	R _L =4Ω, f=1kHz		0.15	%
		P _O =1.0W			0.25	%
		P _O =3.0W			0.25	%
Output Noise	V _N	f=20Hz~20kHz, AWeighting		160		μV _{rms}
Signal-to-Noise Ratio	SNR	AWeighted, Av=26dB, THD+N = 1%		91		dB
Offset voltage	V _{OS}			±6.5		mV
efficiency	η	R _L =4Ω+22uH, THD+N = 10%		90		%
		R _L =8Ω+33uH, THD+N = 10%		94		%
Quiescent Current	I _{DD}	No Load	Input Grounded		10.5	mA
		With Load*6			14	mA
Shutdown current	I _{SD}	No Load	CTRL=V _{SS}		0.5	μA
		With Load*6			0.5	μA
Maximum input signal	V _{IN_max}	f _{IN} = 1kHz, THD+N ≤ 10%, ACF-1 ON		1.75		V _{rms}
System Gain	Av0	R _{IN} =56 kΩ		26.1		dB
Class AB Channel V _{SS} =0V, Av=20dB, Ta=25°C, C _{IN} =0.1uF, Unless otherwise specified						
Output Power	P _O	R _L =4Ω,	f=1kHz, THD+N=10%		9.2	W
		R _L =8Ω			5.2	W
		R _L =4Ω	f=1kHz, THD+N=1%		7.4	W
		R _L =8Ω			4.2	W
Total Harmonic Distortion plus Noise	THD+N	P _O =0.1W	R _L =4Ω, f=1kHz		0.14	%
		P _O =1W			0.12	%
		P _O =3W			0.12	%
Output Noise	V _N	f=20Hz~20kHz, AWeighting		75		μV _{rms}
Signal-to-Noise Ratio	SNR	AWeighted, Av=20dB, THD+N = 1%		97		dB
Offset voltage	V _{OS}			±3		mV
efficiency	η	R _L =4Ω,	f=1kHz, THD+N=10%		80	%
		R _L =8Ω			83.5	%
		R _L =4Ω	f=1kHz, THD+N=1%		72	%
		R _L =8Ω,			76	%
Quiescent Current	I _{DD}	No Load	Input Grounded		31	mA
		With Load*6			31	mA
Shutdown current	I _{SD}	No Load	CTRL=V _{SS}		34	μA
		With Load*6			34	μA
Maximum input signal	V _{IN_max}	f _{IN} = 1kHz, THD+N ≤ 10%, ACF OFF		0.8		V _{rms}
System Gain	Av0	R _{IN} =56 kΩ		18.8		dB

Note6: Load here using 4ohm+22uH to simulate the speaker, the same below.

V_{DD} = 7.2V

parameter	symbol	condition		Minimum	Typical Value	Maximum	unit
Class D Channel V _{SS} =0V, Av=26dB, Ta=25°C, C _{IN} =0.1uF, ACF-OffMode, unless otherwise specified							
Output Power	P _O	R _L =4Ω	f=1kHz, THD+N=10%		7.0		W
		R _L =8Ω			3.8		
		R _L =4Ω,	f=1kHz, THD+N=1%		5.7		
		R _L =8Ω			3.1		
Total Harmonic Distortion plus Noise	THD+N	P _O =0.1W	R _L =4Ω, f=1kHz		0.22		%
		P _O =1.0W			0.17		%
		P _O =3.0W			0.27		%
Output Noise	V _N	f=20Hz~20kHz, AWeighting			150		μV _{rms}
Signal-to-Noise Ratio	SNR	AWeighted, Av=26dB, THD+N = 1%			91		dB
Offset voltage	V _{OS}				±14		mV
Quiescent Current	I _{DD}	No Load	Input Grounded		7.5		mA
		With Load*6			12		mA
Shutdown current	I _{SD}	No Load	CTRL=V _{SS}		0.5		μA
		With Load*6			0.5		μA
Maximum input signal	V _{IN_max}	f _{IN} = 1kHz, THD+N ≤ 10%, ACF-1 ON			1.50		V _{rms}
System Gain	AV ₀	R _{IN} =56 kΩ			26.1		dB
Class AB Channel V _{SS} =0V, Av=20dB, Ta=25°C, C _{IN} =0.1uF, Unless otherwise specified							
Output Power	P _O	R _L =4Ω,	f=1kHz, THD+N=10%		6.7		W
		R _L =8Ω			3.7		W
		R _L =4Ω	f=1kHz, THD+N=1%		5.4		W
		R _L =8Ω			3.0		W
Total Harmonic Distortion plus Noise	THD+N	P _O =0.1W	R _L =4Ω, f=1kHz		0.08		%
		P _O =1W			0.10		%
		P _O =3W			0.13		%
Output Noise	V _N	f=20Hz~20kHz, AWeighting			75		μV _{rms}
Signal-to-Noise Ratio	SNR	AWeighted, Av=20dB, THD+N = 1%			96		dB
Offset voltage	V _{OS}				±3		mV
Quiescent Current	I _{DD}	No Load	Input Grounded		25		mA
		With Load*6			25		mA
Shutdown current	I _{SD}	No Load	CTRL=V _{SS}		28		μA
		With Load*6			28		μA
Maximum input signal	V _{IN_max}	f _{IN} = 1kHz, THD+N ≤ 10%, ACF OFF			0.65		V _{rms}
System Gain	AV ₀	R _{IN} =56 kΩ			18.9		dB

V_{DD} = 6.5V

parameter	symbol	condition	Minimum	Typical Value	Maximum	unit
Class D Channel V _{SS} =0V, A _v =26dB, T _a =25°C, C _{IN} =0.1uF, ACF-OffMode, unless otherwise specified						
Output Power	P _O	R _L =4Ω	f=1kHz, THD+N=10%		5.7	W
		R _L =8Ω			3.1	
		R _L =4Ω,	f=1kHz, THD+N=1%		4.6	
		R _L =8Ω			2.5	
Total Harmonic Distortion plus Noise	THD+N	P _O =0.1W	R _L =4Ω, f=1kHz		0.28	%
		P _O =1.0W			0.15	%
		P _O =3.0W			0.30	%
Output Noise	V _N	f=20Hz~20kHz, AWeighting		150		μV _{rms}
Signal-to-Noise Ratio	SNR	AWeighted, A _v =26dB, THD+N = 1%		90		dB
Offset voltage	V _{OS}			±16		mV
efficiency	η	R _L =4Ω+22uH, THD+N = 10%		90		%
		R _L =8Ω+33uH, THD+N = 10%		94		%
Quiescent Current	I _{DD}	No Load	Input Grounded		6.5	mA
		With Load*6			11	mA
Shutdown current	I _{SD}	No Load	CTRL=V _{SS}		0.5	μA
		With Load*6			0.5	μA
Maximum input signal	V _{IN_max}	f _{IN} = 1kHz, THD+N ≤ 10%, ACF-1 ON		1.35		V _{rms}
System Gain	A _{V0}	R _{IN} =56 kΩ		26.1		dB
Class AB Channel V _{SS} =0V, A _v =20dB, T _a =25°C, C _{IN} =0.1uF, Unless otherwise specified						
Output Power	P _O	R _L =4Ω,	f=1kHz, THD+N=10%		5.5	W
		R _L =8Ω			3.1	W
		R _L =4Ω	f=1kHz, THD+N=1%		4.4	W
		R _L =8Ω			2.5	W
Total Harmonic Distortion plus Noise	THD+N	P _O =0.1W	R _L =4Ω, f=1kHz		0.08	%
		P _O =1W			0.10	%
		P _O =3W			0.13	%
Output Noise	V _N	f=20Hz~20kHz, AWeighting		73		μV _{rms}
Signal-to-Noise Ratio	SNR	AWeighted, A _v =20dB, THD+N = 1%		95		dB
Offset voltage	V _{OS}			±3		mV
efficiency	η	R _L =4Ω,	f=1kHz, THD+N=10%		80	%
		R _L =8Ω			84	%
		R _L =4Ω	f=1kHz, THD+N=1%		72.5	%
		R _L =8Ω,			76	%
Quiescent Current	I _{DD}	No Load	Input Grounded		twenty four	mA
		With Load*6			twenty four	mA
Shutdown current	I _{SD}	No Load	CTRL=V _{SS}		25	μA
		With Load*6			25	μA
Maximum input signal	V _{IN_max}	f _{IN} = 1kHz, THD+N ≤ 10%, ACF OFF		0.58		V _{rms}
System Gain	A _{V0}	R _{IN} =56 kΩ		19.1		dB

V_{DD} = 5.0V

parameter	symbol	condition		Minimum	Typical Value	Maximum	unit
Class D Channel V _{SS} =0V, A _v =26dB, T _a =25°C, C _{IN} =0.1uF, ACF-OffMode, unless otherwise specified							
Output Power	P _O	R _L =4Ω	f=1kHz, THD+N=10%		3.35		W
		R _L =8Ω			1.85		
		R _L =4Ω,	f=1kHz, THD+N=1%		2.72		
		R _L =8Ω			1.5		
Total Harmonic Distortion plus Noise	THD+N	P _O =0.1W	R _L =4Ω, f=1kHz		0.13		%
		P _O =1.0W			0.15		%
Output Noise	V _N	f=20Hz~20kHz, AWeighting			150		μV _{rms}
Signal-to-Noise Ratio	SNR	AWeighted, A _v =26dB, THD+N = 1%			87		dB
Offset voltage	V _{OS}				±15		mV
Quiescent Current	I _{DD}	No Load	Input Grounded		5.5		mA
		With Load*6			9		mA
Shutdown current	I _{SD}	No Load	CTRL=V _{SS}		0.5		μA
		With Load*6			0.5		μA
Maximum input signal	V _{IN_max}	f _{IN} = 1kHz, THD+N ≤ 10%, ACF-1 ON			1.0		V _{rms}
System Gain	A _{V0}	R _{IN} =56 kΩ			26.2		dB
Class AB Channel V _{SS} =0V, A _v =20dB, T _a =25°C, C _{IN} =0.1uF, Unless otherwise specified							
Output Power	P _O	R _L =4Ω,	f=1kHz, THD+N=10%		3.2		W
		R _L =8Ω			1.8		
		R _L =4Ω	f=1kHz, THD+N=1%		2.6		
		R _L =8Ω			1.45		
Total Harmonic Distortion plus Noise	THD+N	P _O =0.1W	R _L =4Ω, f=1kHz		0.08		%
		P _O =1W			0.11		%
Output Noise	V _N	f=20Hz~20kHz, AWeighting			70		μV _{rms}
Signal-to-Noise Ratio	SNR	AWeighted, A _v =20dB, THD+N = 1%			93		dB
Offset voltage	V _{OS}				±3		mV
Quiescent Current	I _{DD}	No Load	Input Grounded		twenty one		mA
		With Load*6			twenty one		mA
Shutdown current	I _{SD}	No Load	CTRL=V _{SS}		19		μA
		With Load*6			19		μA
Maximum input signal	V _{IN_max}	f _{IN} = 1kHz, THD+N ≤ 10%, ACF OFF			0.42		V _{rms}
System Gain	A _{V0}	R _{IN} =56 kΩ			19.4		dB

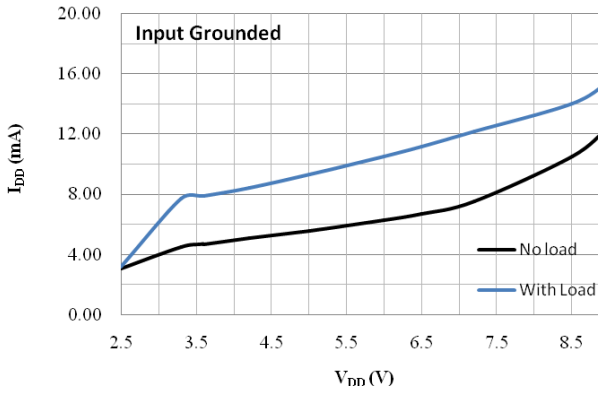
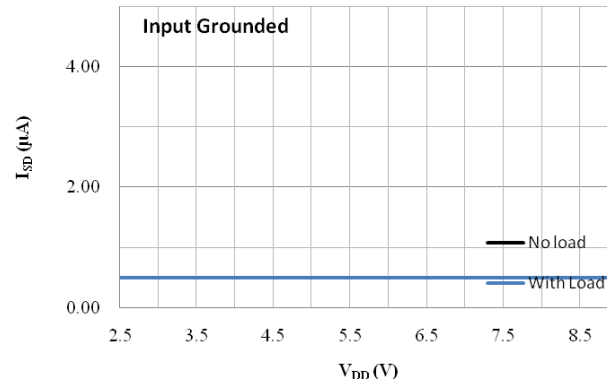
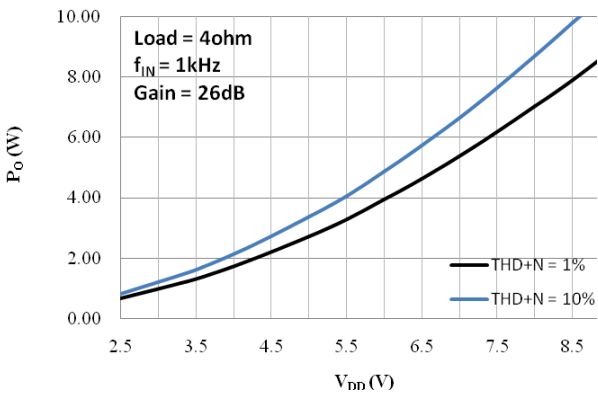
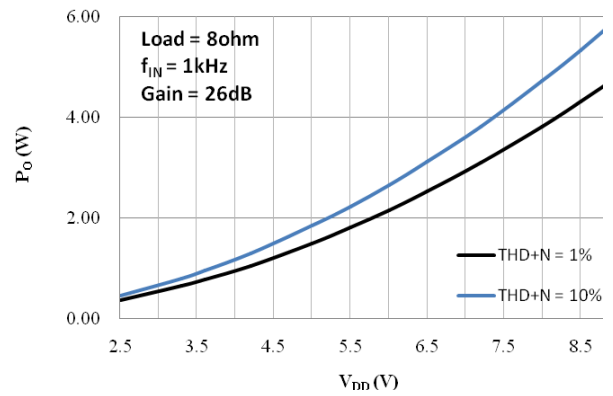
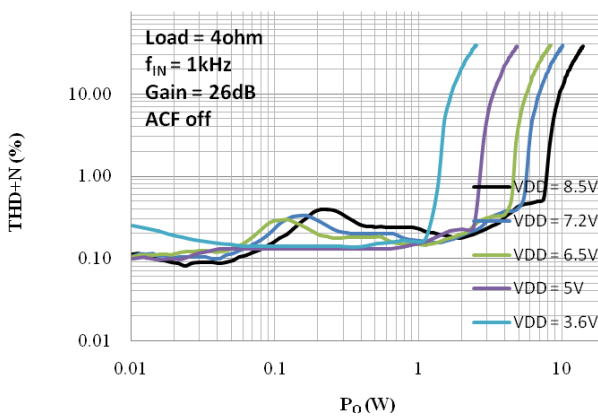
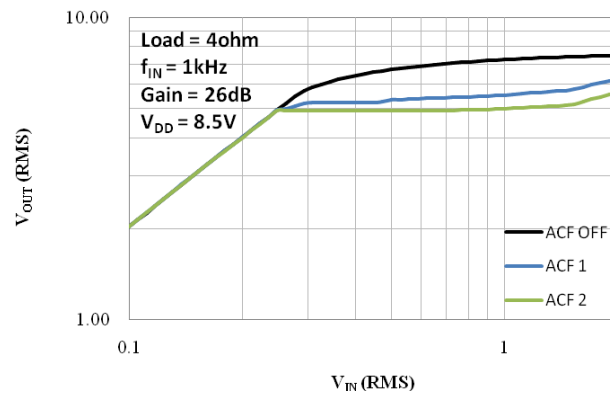
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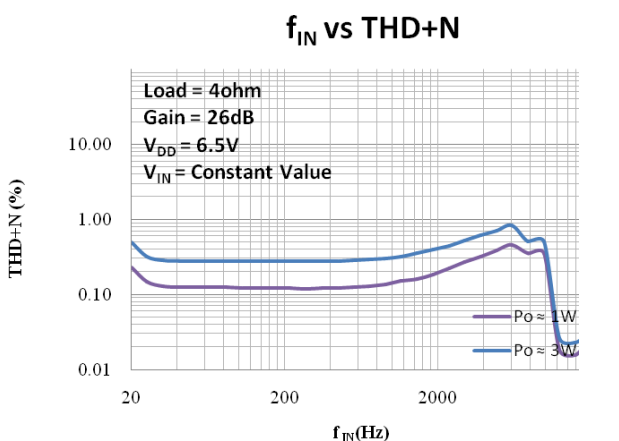
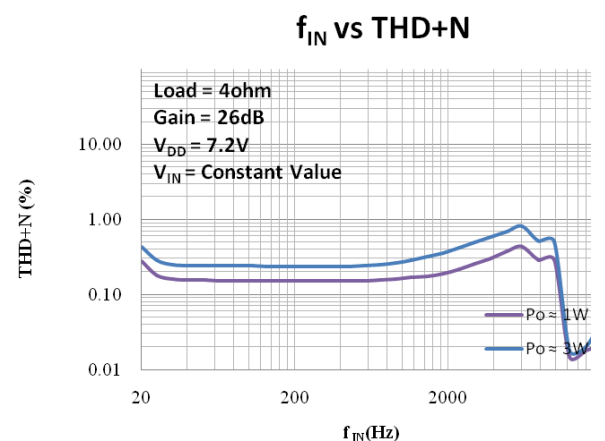
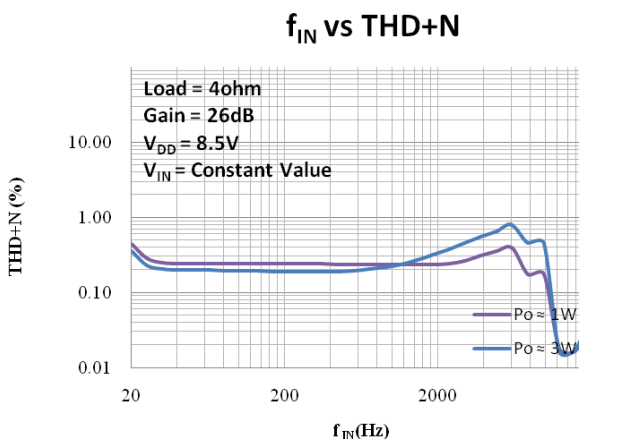
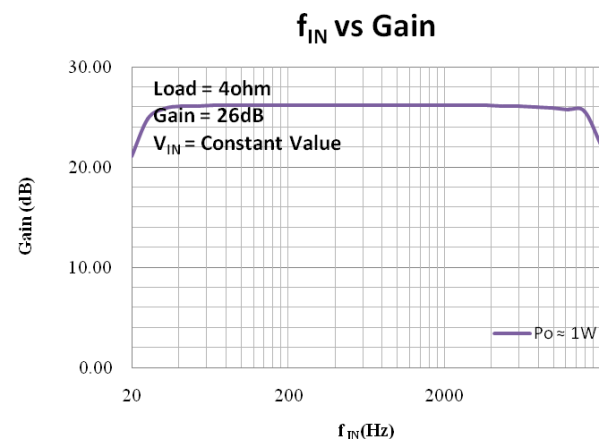
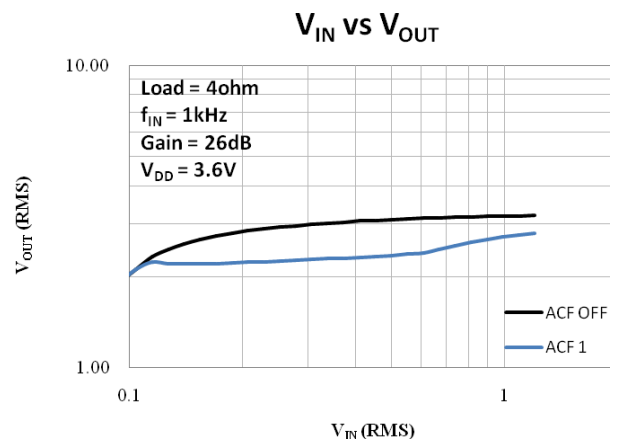
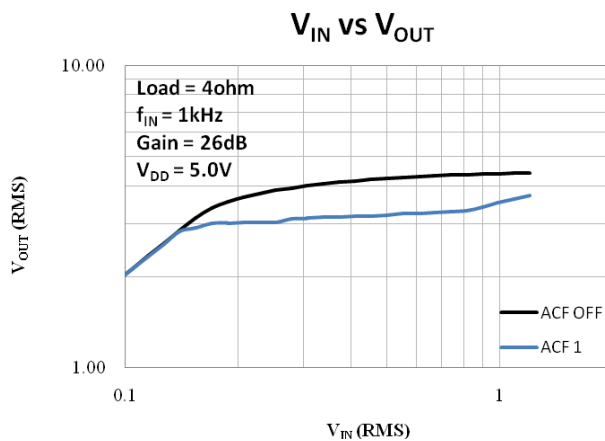
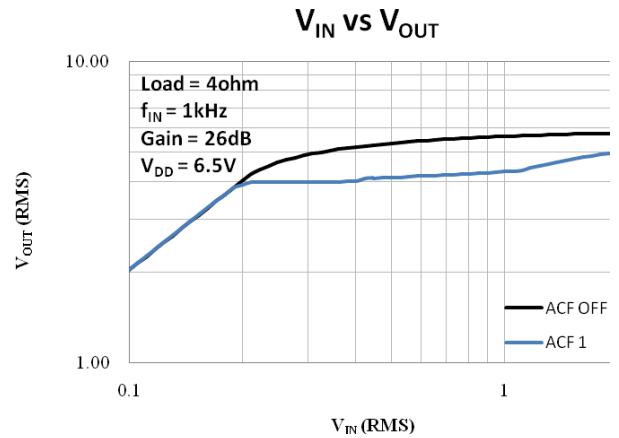
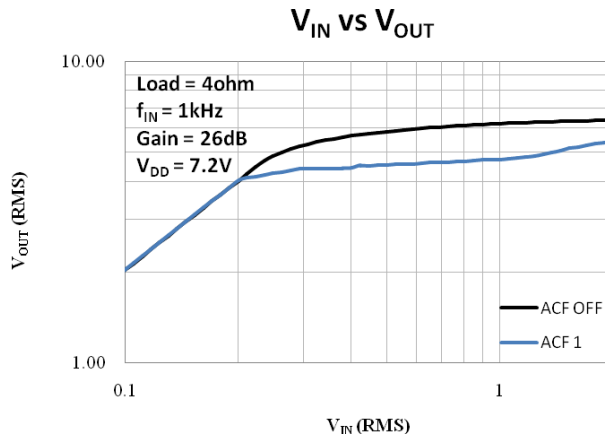
parameter	symbol	condition	Minimum	Typical Value	Maximum	unit
Class D Channel V _{SS} =0V, Av=26dB, Ta=25°C, C _{IN} =0.1uF, ACF-OffMode, unless otherwise specified						
Output Power	P _O	R _L =4Ω	f=1kHz, THD+N=10%	1.7		W
		R _L =8Ω		0.95		
		R _L =4Ω,	f=1kHz, THD+N=1%	1.4		
		R _L =8Ω		0.75		
Total Harmonic Distortion plus Noise	THD+N	P _O =0.1W	R _L =4Ω, f=1kHz	0.14		%
		P _O =1.0W		0.16		%
Output Noise	V _N	f=20Hz~20kHz, AWeighting		140		μV _{rms}
Signal-to-Noise Ratio	SNR	AWeighted, Av=26dB, THD+N = 1%		85		dB
Offset voltage	V _{OS}			±13		mV
efficiency	η	R _L =4Ω+22uH, THD+N = 10%		88		%
		R _L =8Ω+33uH, THD+N = 10%		93		%
Quiescent Current	I _{DD}	No Load	Input Grounded	4.5		mA
		With Load*6		7.8		mA
Shutdown current	I _{SD}	No Load	CTRL=V _{SS}	0.5		μA
		With Load*6		0.5		μA
Maximum input signal	V _{IN_max}	f _{IN} = 1kHz, THD+N ≤ 10%, ACF-1 ON		0.70		V _{rms}
System Gain	AV ₀	R _{IN} =56 kΩ		26.2		dB
Class AB Channel V _{SS} =0V, Av=20dB, Ta=25°C, C _{IN} =0.1uF, Unless otherwise specified						
Output Power	P _O	R _L =4Ω,	f=1kHz, THD+N=10%	1.65		W
		R _L =8Ω		0.9		W
		R _L =4Ω	f=1kHz, THD+N=1%	1.3		W
		R _L =8Ω		0.75		W
Total Harmonic Distortion plus Noise	THD+N	P _O =0.1W	R _L =4Ω, f=1kHz	0.09		%
		P _O =1W		0.13		%
Output Noise	V _N	f=20Hz~20kHz, AWeighting		70		μV _{rms}
Signal-to-Noise Ratio	SNR	AWeighted, Av=20dB, THD+N = 1%		90		dB
Offset voltage	V _{OS}			±3		mV
efficiency	η	R _L =4Ω,	f=1kHz, THD+N=10%	79		%
		R _L =8Ω		84		%
		R _L =4Ω	f=1kHz, THD+N=1%	72		%
		R _L =8Ω,		76		%
Quiescent Current	I _{DD}	No Load	Input Grounded	19		mA
		With Load*6		19		mA
Shutdown current	I _{SD}	No Load	CTRL=V _{SS}	13.5		μA
		With Load*6		13.5		μA
Maximum input signal	V _{IN_max}	f _{IN} = 1kHz, THD+N ≤ 10%, ACF OFF		0.30		V _{rms}
System Gain	AV ₀	R _{IN} =56 kΩ		19.6		dB

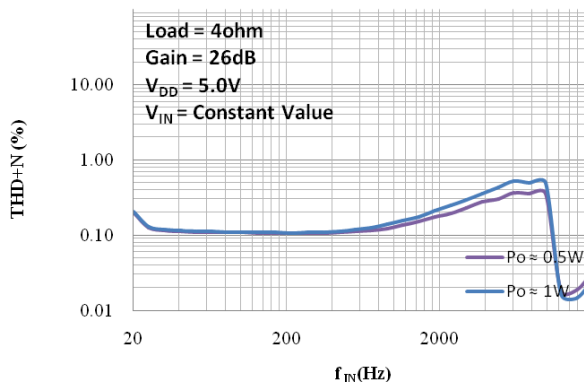
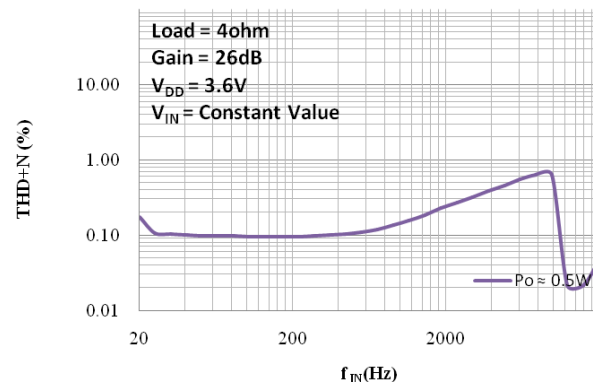
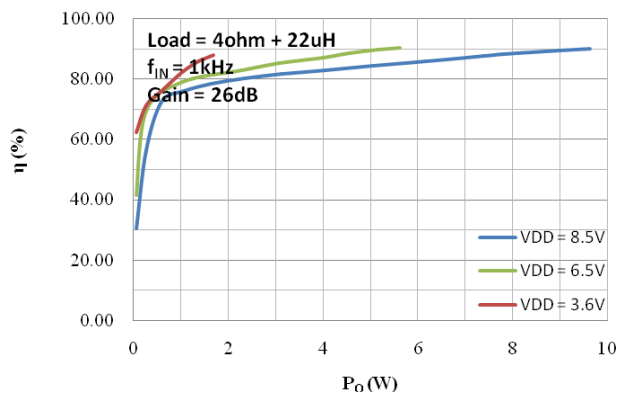
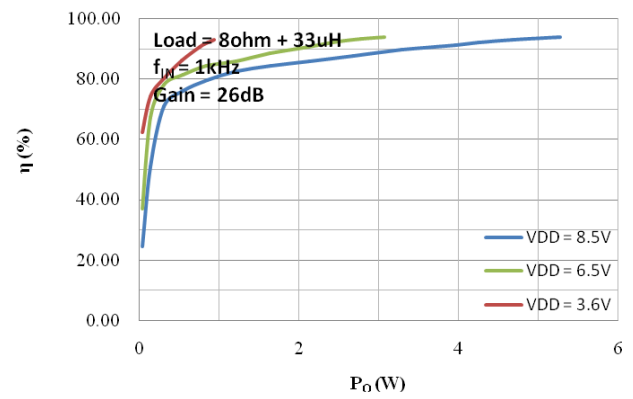
-Typical characteristic curve

Class D Channel

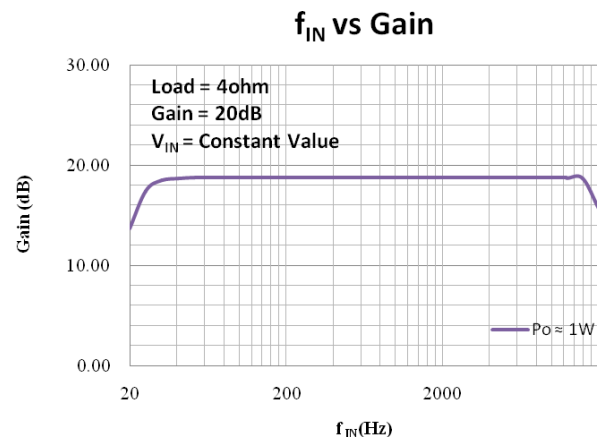
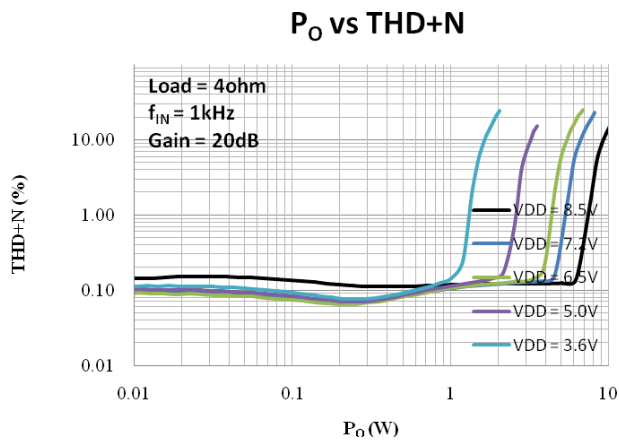
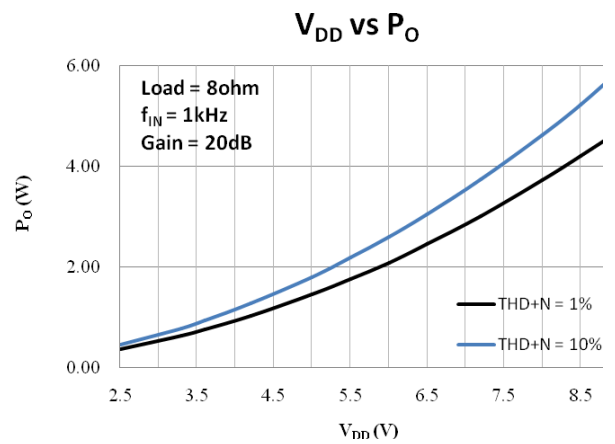
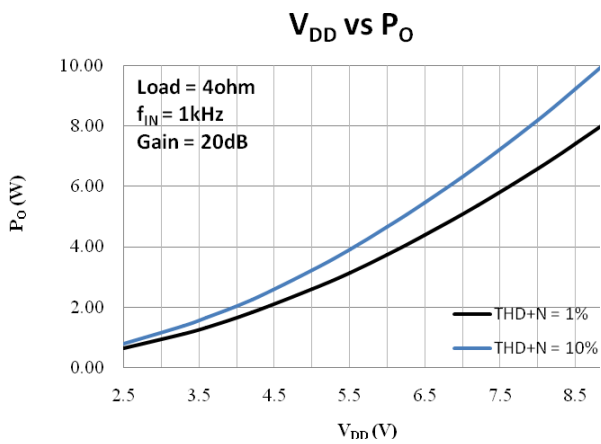
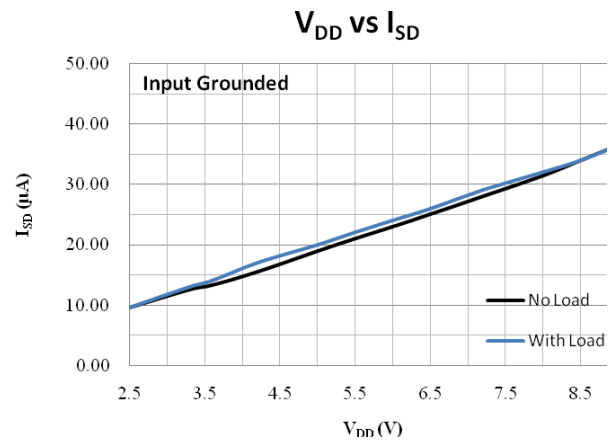
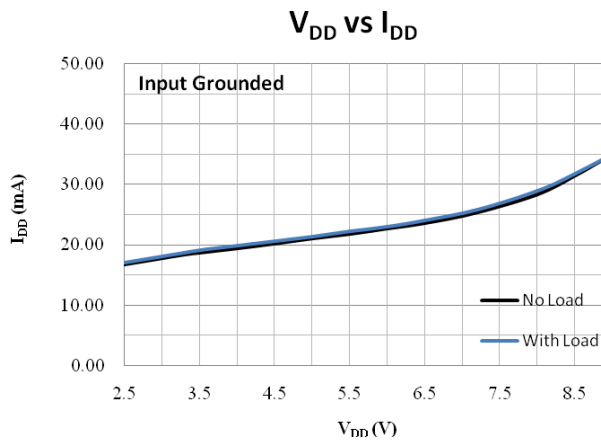
 Condition: Class D mode, $V_{DD} = 2.5\sim 8.5V$, $f_{IN} = 1kHz$, $R_{IN} = 56k$, ACF off, Output = Load + Filter, Load = 4ohm, Filter = 100ohm + 47nF, unless otherwise specified

 V_{DD} vs I_{DD}

 V_{DD} vs I_{SD}

 V_{DD} vs P_O

 V_{DD} vs P_O

 P_O vs THD+N

 V_{IN} vs V_{OUT}


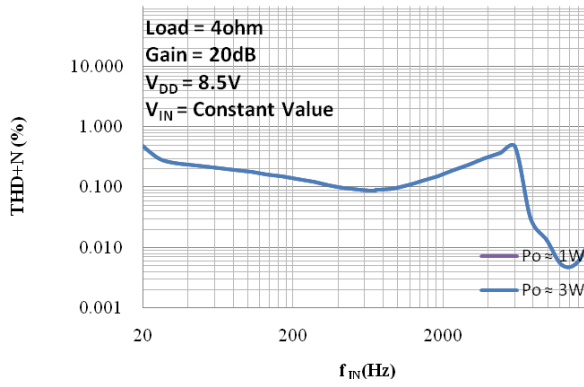


f_{IN} vs THD+N

 f_{IN} vs THD+N

 P_O vs η

 P_O vs η


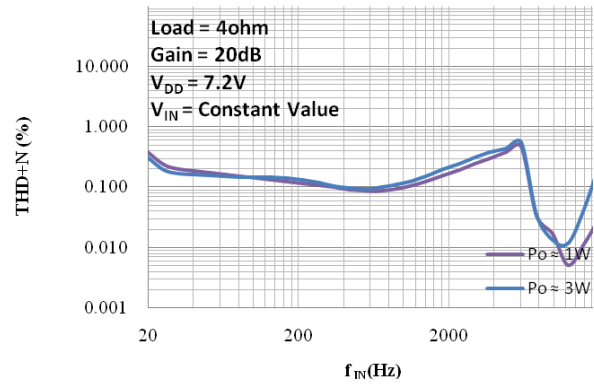
Class AB Channel

 Condition: Class AB mode, $V_{DD} = 2.5\sim 8.5V$, $f_{IN} = 1kHz$, $R_{IN} = 56k$, Output = Load = 4ohm, unless otherwise specified.


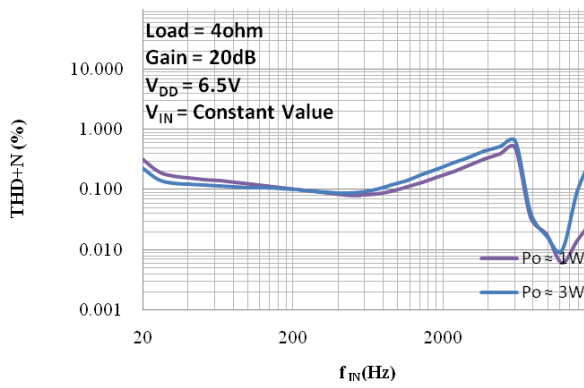
f_{IN} vs THD+N



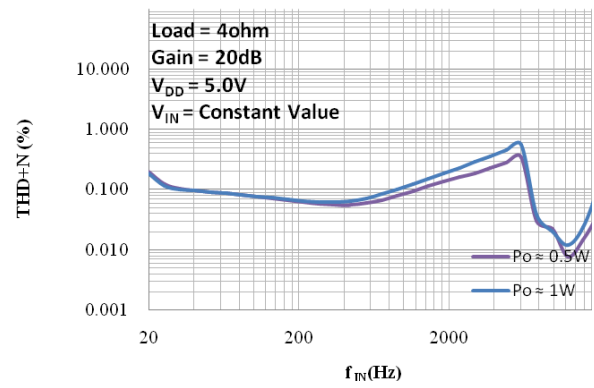
f_{IN} vs THD+N



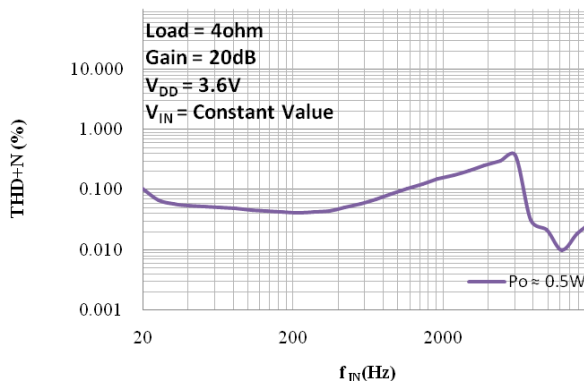
f_{IN} vs THD+N



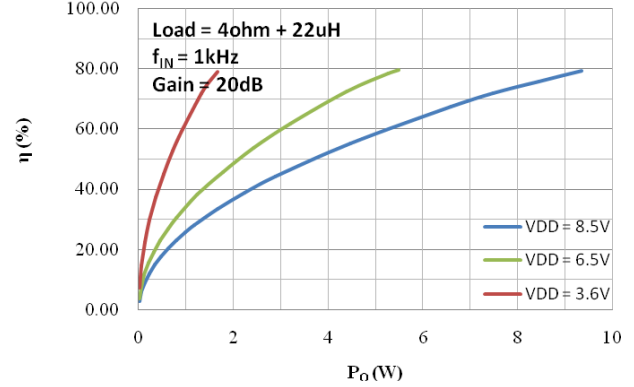
f_{IN} vs THD+N



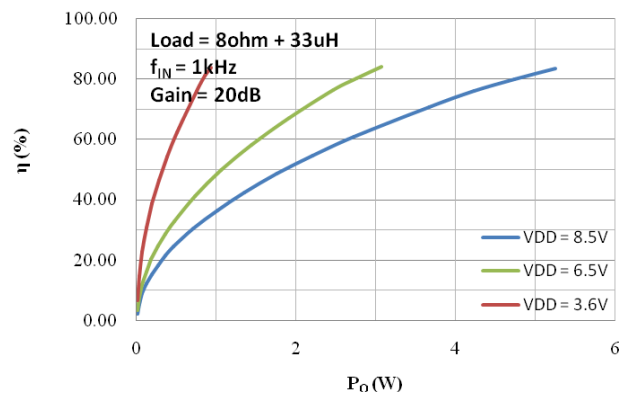
f_{IN} vs THD+N



P_O vs η



P_O vs η



Functional description and application information
-Input Configuration

HT8693 Accepts analog differential or single-ended audio signal input and generates PWM. The pulse output signal drives the speaker.

For differential input, use a DC blocking capacitor C_{IN} and input resistance R_{IN} Enter into $IN+$ and $IN-$. System gain $A_v = 1/50k R_{IN}$ (D class mode) or $A_v = 500k/R_{IN}$ (AB class mode), input RC high pass filter cutoff frequency $f_c = 1/(2\pi R_{IN} C_{IN})$.

For single-ended input, C_{IN} Coupling to $IN+$ end. $IN-$ The input resistor and capacitor must be connected to the C_{IN} , R_{IN} same value) to ground. Gain A_v and cutoff frequency f_c Same as differential input.

Pay attention to the output impedance of the system's front-end circuit Z_{OUT} Should not exceed 600Ω .

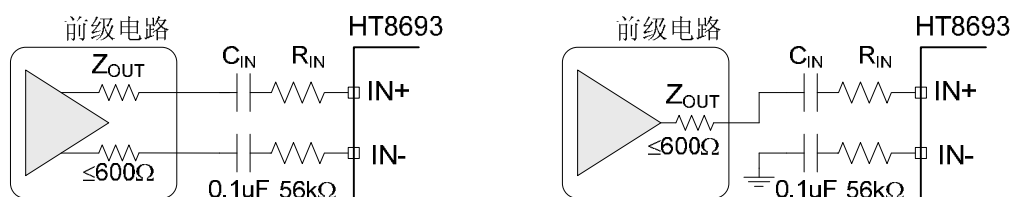


chart1(1) Differential input;

(2) Single-ended input

-Amplifier Output

Generally speaking, the output terminal can be directly connected to the load speaker. EMI If the requirements are higher, you can choose to add ferrite beads or LC filter.

In addition, if the power supply voltage is large ($>8.5V$), the ripple is serious, or the input signal amplitude is large ($\geq 1.0V_{rms}$), or the load speaker impedance is small ($<4\Omega$), it is necessary to appropriately increase the power supply capacitance (at least $100\mu F$ above), and add Snubber Circuit and Schottky diode (as shown in 2), to prevent chip abnormality.

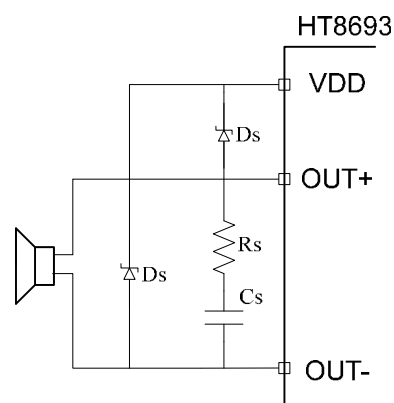


chart2 Output Connections

Recommended parameters:

R_s : $1.5 \sim 2\Omega$;

C_s : $330pF \sim 680pF$;

D_s : Average forward current $\geq 2A$; Forward surge peak current $\geq 6A$; Forward Voltage ($I_F = 2A$) $\leq 0.5V$.

-ABD Mode Settings

exist ABD The input terminal is high level. HT8693 In Class D Mode, system gain $A_v = 1/150k R_{IN}$.

exist ABD The input is low level. HT8693 In Class AB Mode, system gain $A_v = 500k R_{IN}$.

have to be aware of is, ABD The pin supports floating, and there is an internal pull-up resistor with a resistance of approximately $250k\Omega$.

-CTRLMode Settings

Class DIn mode,CTRLDifferent voltage values can be input to achieve4Working mode, namely anti-top cutting mode1 (ACF-1), anti-top clipping mode2 (ACF-2), anti-top clipping function off mode (ACF-Off) and chip shutdown mode (SD), see the table below for details.

sheet1 CTRLInput voltage for different pin modes

parameter name	symbol	Minimum	Typical Value	Maximum	unit
ACF-OffMode setting threshold voltage	V_{MOD1}	$0.75V_{DD}$		V_{DD}	V
ACF-1Mode setting threshold voltage	V_{MOD2}	$0.45V_{DD}$		$0.70V_{DD}$	V
ACF-2Mode setting threshold voltage	V_{MOD3}	$0.10V_{DD}$		$0.40V_{DD}$	V
SD Mode setting threshold voltage	V_{MOD4}	VSS		$0.06V_{DD}$	V

In configurationCTRLWhen the external voltage is applied to the terminal, it should be noted that there is an internal120KohmPull-down resistor, as shown below.ABIn class mode, there is no pull-down resistor.

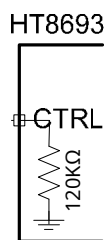


chart3 CTRLInternal resistance

in addition,SDAAfter shutting down, re-enable the chip.CTRLThe end needs to be at least0.8Vvoltage.

-CTRLMode Function Description
(one)ACF ONmodel

existACF-1,ACF-2In this mode, when the circuit detects that the input signal amplitude is too large and the output is clipped,HT8693By automatically adjusting the system gain, the output is controlled to achieve a maximum power level without clipping distortion, thereby greatly improving the sound quality. In addition, when the power supply voltage drops,HT8693It can also automatically attenuate the output gain to achieve the same V_{DD} The drop value matches the maximum non-clipping output level.

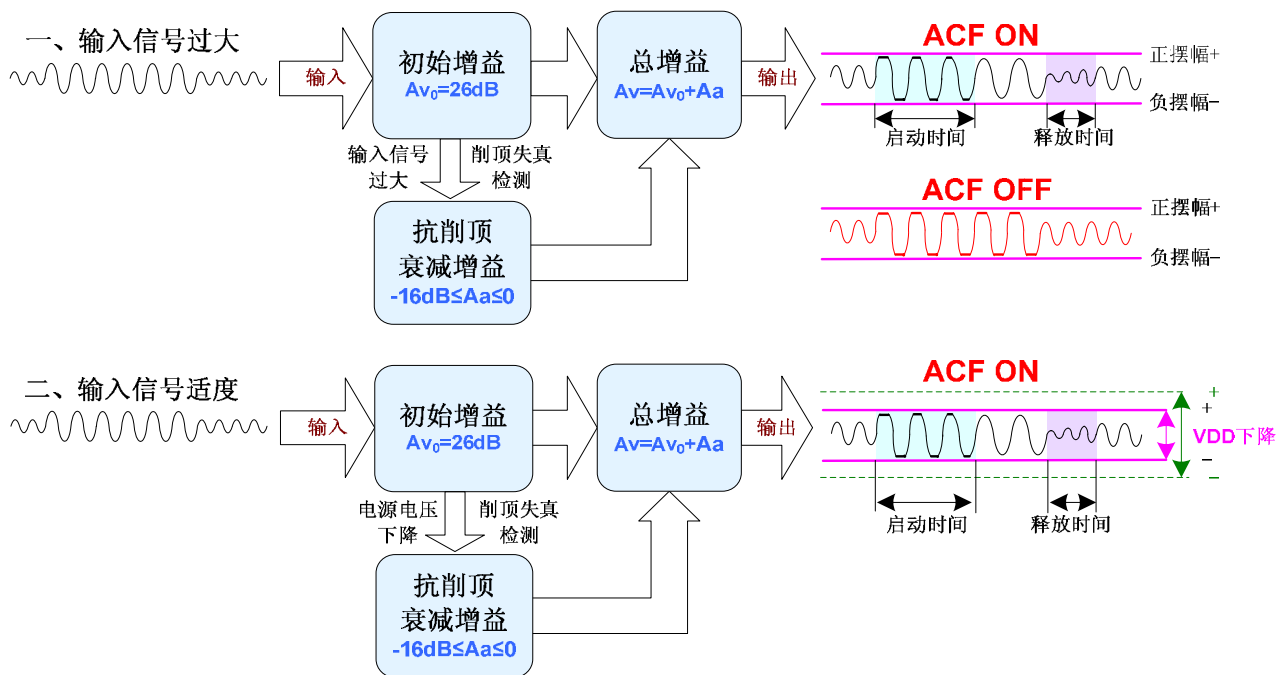


chart4 ACFWorking principle diagram

ACF ONStartup time in mode (Attack time) refers to the condition where a sufficiently large signal is suddenly input to produce output clipping. ACF Start adjusting the gain of the amplifier until the gain changes from A_{vo} Attenuation to target attenuation gain 3dB . The time interval from when the input condition Release time (Release time) when the gain exits the attenuation state and returns to A_{vo} time interval. HT8693 The maximum attenuation gain is 16dB .

ACF-1 and ACF-2 Modes have different attack and release times (see table below).

sheet2 ACF-1 and ACF-2 Mode Difference

model	Start Time	Release time
ACF-1	50ms	64ms
ACF-2	2.5ms	1200ms

(two) ACF OFF model

exist ACF-Off Mode, ACF The function is turned off. HT8693 No output clipping condition is detected, and no automatic adjustment is performed on the system gain. The system gain remains at $A_v = A_{vo} = 26\text{dB}$ Constant. HT8693 The sound quality may deteriorate due to output distortion.

(three) SD model

In shutdown mode (low-power standby), the chip turns off all functions and reduces power consumption to a minimum, and the output is in a weak low level state (internally connected to ground through a high resistance).

-Click-and-Pop Elimination

HT8693 The built-in control circuit achieves comprehensive noise suppression, effectively suppressing transient clicks and pops that occur during system power-on, power-off, shutdown and wake-up operations. Click-Pop) noise.

To achieve better click-pop noise elimination, it is generally recommended to use $0.1\mu\text{F}$ For smaller DC blocking capacitor C_{in} . at the same time POP Noise can also be minimized by the following timing control measures for shutdown mode during power-up and power-down:

- When the power supply is powered on, keep the shutdown mode, and then release the shutdown mode after the power supply is stable enough. •
- When the power is turned off, set it to shutdown mode in advance.

-Protective function

HT8693 It has the following protection functions: output overcurrent protection, on-chip overtemperature protection, and power supply undervoltage protection.

(1) Overcurrent protection

When a short circuit is detected between one output terminal and the power supply, ground, or another output terminal, the overcurrent protection is activated and the output terminal switches to a high impedance state to prevent the chip from burning and damaging. After the short circuit is eliminated, the chip can be shut down, wake up once, or power on again to exit the protection mode.

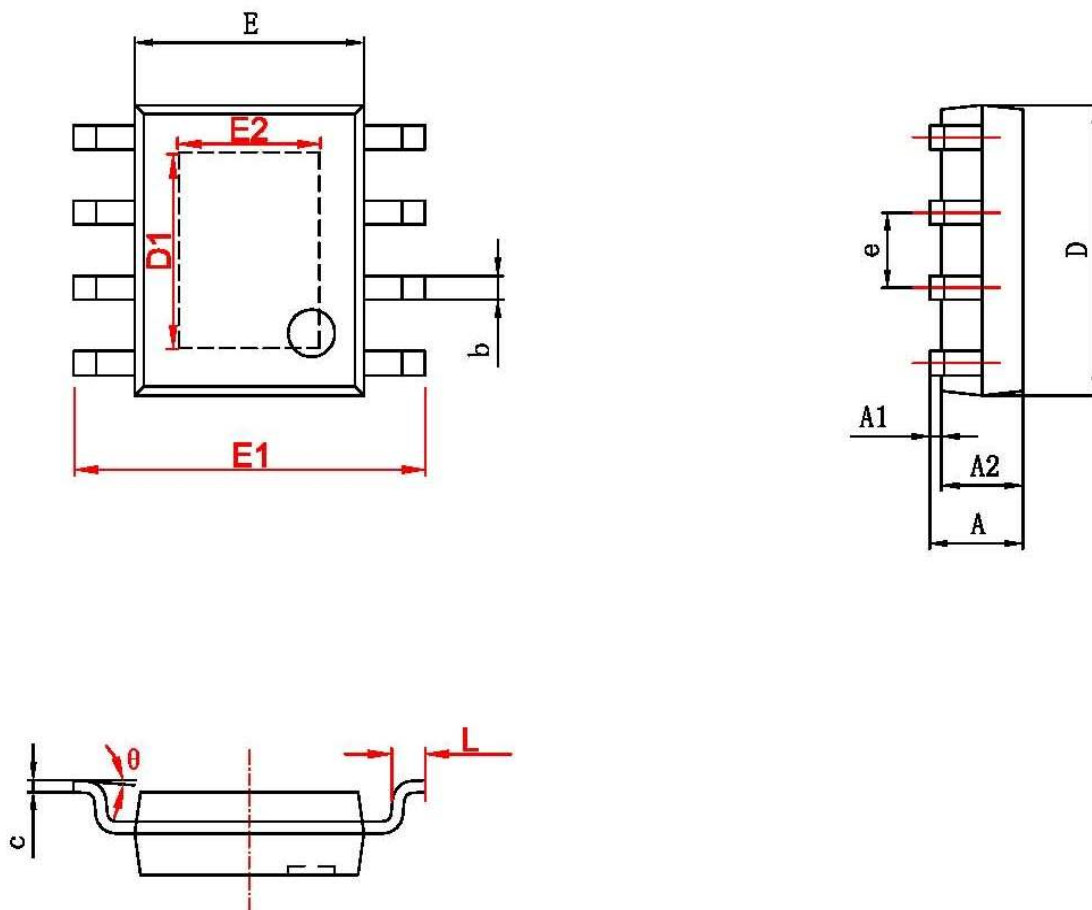
(2) Overtemperature protection

When the chip temperature exceeds 150°C , the over-temperature protection starts, and the positive and negative output terminals switch to a weak low level state (internally connected to ground through a high resistance) to prevent the chip from being damaged by thermal breakdown.

(3) Undervoltage protection

When the power supply is detected V_{DD} Lower than V_{UVL} , start undervoltage protection, the output end is in a weak low level state (internal grounding through high resistance) When testing arrive V_{DD} Higher than V_{UVL} , the protection mode is automatically released after the startup time T_{STUP} Then enter normal working state.

-Package Outline

SOP8-PP(EXP PAD) PACKAGE OUTLINE DIMENSIONS


字符	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
A	1.350	1.750	0.053	0.069
A1	0.050	0.150	0.002	0.006
A2	1.350	1.550	0.053	0.061
b	0.330	0.510	0.013	0.020
c	0.170	0.250	0.007	0.010
D	4.700	5.100	0.185	0.200
D1	3.202	3.402	0.126	0.134
E	3.800	4.000	0.150	0.157
E1	5.800	6.200	0.228	0.244
E2	2.313	2.513	0.091	0.099
e	1.270 (BSC)		0.050 (BSC)	
L	0.400	1.270	0.016	0.050
θ	0°	8°	0°	8°

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